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1	Linking in situ LAI and fine resolution remote sensing data to map reference LAI
2	over cropland and grassland using geostatistical regression method
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24	Abstract: Leaf Area Index (LAI) is an important parameter of vegetation structure. A
25	number of moderate resolution LAI products have been produced in urgent need of large
26	scale vegetation monitoring. High resolution LAI reference maps are necessary to
27	validate these LAI products. This study used a geostatistical regression (GR) method to
28	estimate LAI reference maps by linking in situ LAI and Landsat TM/ETM+ and SPOT-
29	HRV data over two cropland and two grassland sites. To explore the discrepancies of
30	employing different vegetation indices (VIs) on estimating LAI reference maps, this
31	study established the GR models for different VIs, including difference vegetation index
32	(DVI), normalized difference vegetation index (NDVI), and ratio vegetation index (RVI).
33	To further assess the performance of the GR model, the results from the GR and Reduced
34	Major Axis (RMA) models were compared. The results show that the performance of the
35	GR model varies between the cropland and grassland sites. At the cropland sites, the GR
36	model based on DVI provides the best estimation, while at the grassland sites, the GR
37	model based on DVI performs poorly. Compared to the RMA model, the GR model
38	improves the accuracy of reference LAI maps in terms of root mean square errors (RMSE)
39	and bias.

41 Keywords: Leaf Area Index; Up-scaling; Geostatistical Regression; Reduced Major Axis;
42 Vegetation Index

43 1. Introduction

44 Leaf Area Index (LAI), defined as half the total leaf area per unit ground surface 45 areas (Chen and Black, 1992), is an important parameter of vegetation structure and 46 function (Abuelgasim et al., 2006). LAI provides substantial information on the exchange 47 of energy, mass, and momentum flux between the Earth's surface and its atmosphere 48 (Morisette et al., 2006; Myneni et al., 1997). LAI has been widely used as an input in 49 climate, hydrology, and biogeochemistry models (Berterretche et al., 2005; Knyazikhin et 50 al., 1998; Morisette et al., 2006). To date, a number of global and regional moderate-51 resolution LAI products have been produced, including Moderate Resolution Imaging 52 Spectroradiometer (MODIS), Carbon Cycle and Change in Land Observational Products 53 from and Ensemble of Satellites (CYCLOPES), Canada Centre for Remote Sensing 54 (CCRS), and Global Land Surface Satellite (GLASS) (Chen et al., 2002; Tian et al., 55 2000; Weiss et al., 2007; Xiao et al., 2014). Owing to the influence of model algorithms, 56 vegetation heterogeneity, and observation conditions, these LAI products inevitably have 57 inherent uncertainties (Chen et al., 2002), which subsequently may impact the accuracy 58 of any resulting modeling activities. Specifying the uncertainties of these coarse spatial 59 resolution LAI products is essential for users to determine the most appropriate dataset 60 for their applications, and for producers to improve methodological algorithms. However, 61 a direct comparison between in situ LAI measurements and these corresponding 62 moderate resolution LAI products is not recommended because of scale-mismatch, 63 geolocation errors, and land surface heterogeneity (Huang et al., 2006; Yang et al., 2006). 64 The proposed way to validate coarse resolution remote sensing products is using fine 65 reference maps derived from up-scaling in situ measurements (Fernandes et al., 2014;

66	Iiames et al., 2015; Kang et al., 2015; Morisette et al., 2006; Wang et al., 2014). Previous
67	studies have generated fine resolution LAI reference maps through fusing in situ LAI
68	measurements and fine resolution remote sensing images (e.g. TM, ETM+, ASTER,
69	SPOT) (Baret et al., 2005; Chen et al., 2002; Cohen and Justice, 1999; Garrigues et al.,
70	2008; Li et al., 2013a; Martinez et al., 2009; Morisette et al., 2006; Pisek and Chen,
71	2007).

72 There are three categories of methods for estimating reference LAI maps using in 73 situ LAI observations and fine spatial resolution remote sensing data, including 74 regression, vegetation radiation transfer equation inversion, and geostatistical methods 75 (Cohen et al., 2003; Martinez et al., 2010; Yang et al., 2006). Of these, the radiation 76 transfer equation inversion method is not used widely due to the difficulty in collecting 77 certain model parameters (e.g. canopy structure) and the fact that the solution of the 78 model is not unique (Yang et al., 2006). Geostatistical methods have become popular in 79 linking field data to image data, and been applied to estimate forest parameters (basal 80 area, height, health conditions, etc), detect land use and land cover change, and map 81 vegetation index (e.g., normalized difference vegetation index: NDVI and LAI) (Van der 82 Meer, 2012). Traditional geostatistical methods, such as Kriging, predict unknown points 83 through spatially interpolating surrounding field observations (Berterretche et al., 2005; 84 Li et al., 2013a; Li et al., 2013b). The limited number of field observations and the spatial 85 non-stationarity of in situ observations distribution could lead to uncertainty of predicting 86 results. Regression methods, such as ordinary least squares regression, attempt to 87 improve the predicting accuracy through accounting for high resolution remote sensing 88 data (e.g., reflectance or vegetation indices (VI) derived from Landsat ETM+). Cohen et

al. (2003) compared three regression methods (i.e., traditional ordinary least squares
regression, inverse ordinary least square regression, and reduced major axis: RMA) over
the BigFoot AGRO and NOBS sites. They reported that the performance of RMA method
was superior to the other two. However, none of the regression methods consider the
spatial/temporal correlation of in situ observations and high resolution reflectance or VI
data, which may lead to an underestimation of the uncertainty along with the regression
coefficients (Chatfield, 2003).

96 Geostatistical regression (GR) method conserves merits from both traditional 97 geostatistical methods and regression methods. It has been used in examining the 98 relationships between terrestrial carbon dioxide flux and its primary environmental 99 drivers (Mueller et al., 2010), and estimating snow cover and gross primary productivity 100 (Erickson et al., 2005; Yadav et al., 2010). Compared to traditional regression methods, 101 the GR method is improved in one distinct way, which is the ability to account for the 102 spatial/temporal correlation of the residuals from in situ observations (such as field LAI 103 measurements) and auxiliary data (such as NDVI) (Erickson et al., 2005; Mueller et al., 104 2010; Yadav et al., 2010). Unlike traditional geostatistcal methods (e.g., Kriging), the GR 105 method attempts to provide better estimating of unknown points by exploring the 106 correlation between high resolution remote sensing data and field observations. To our 107 knowledge, no attempts have been made to use the GR method to estimate LAI reference 108 maps. This study applied the GR method to estimate high resolution LAI reference maps 109 over cropland and grassland sites through fusing in situ LAI measurements and high 110 resolution remote sensing images (i.e., Landsat TM/ETM+ and SPOT). To investigate the 111 discrepancy of employing different VIs on estimating LAI reference maps, this study

- 112 established the GR models for the following VIs: difference vegetation index (DVI),
- 113 NDVI, and ratio vegetation index (RVI). To robustly assess the performance of the GR
- 114 model, the results from GR and RMA models were compared.
- 115

116 **2. Methodology**

- 117 2.1. Geostatistical regression method
- 118 The GR method not only models the relationships between auxiliary variables
 119 (DVI, NDVI, and RVI in this study) and field measurements (in situ LAI measurements
 120 in this study), but also accounts for the spatial/temporal correlation of the regression
 121 residuals (Erickson et al., 2005). As with the linear regression method, the GR method
 122 decomposes LAI into a deterministic and a stochastic component:

$$LAI = X\beta + \varepsilon \tag{1}$$

124 Where $X(n \times P)$ is the DVI, NDVI, and RVI, respectively, $\beta(P \times 1)$ is the 125 corresponding regression coefficient, and $\varepsilon(n \times 1)$ is assumed to be second-order 126 stationary and zero-mean residuals for DVI, NDVI, and RVI (Leung and Cooley, 2014;

- 127 Mueller et al., 2010; Yadav et al., 2010). Unlike the traditional linear regression
- 128 approach, which regards ε as white noise, the GR method uses spatial covariance to
- 129 recognize the spatial autocorrelation structure of the regression residuals ε . The
- 130 experimental covariance of residuals ε for DVI, NDVI and RVI, respectively, is:
- 131 $Q(h) = E(\varepsilon(X)\varepsilon(X+h))$ (2)

Where *h* is the spatial and/ or temporal distance, *Q(h)* is the covariance of
residual at separation distance *h* (Erickson et al., 2005). Many theoretical covariance
functions (such as nugget, exponential, spherical, and Gaussian functions) can be used to

model the experimental covariance (Schabenberger and Pierce, 2001). In this study, a
linear combination of nugget and exponential functions is used following the previous
studies (Erickson et al., 2005; Li et al., 2013a; Mueller et al., 2010). This function is
defined as:

139
$$Q(h) = \begin{cases} \sigma_N^2 + \sigma_S^2, h = 0\\ \sigma_S^2 \exp\left(-\frac{h}{l}\right), h > 0 \end{cases}$$
(3)

140 σ_N^2 is the measurement error or the variability at small scale that is uncorrelated in 141 space and/or time, σ_S^2 is the variance of the variability correlated in space and/or time, 142 and *l* is the correlation range parameters (Leung and Cooley, 2014). The Restricted 143 Maximum Likelihood (RML), which maximizes the marginal distribution of the 144 covariance function parameters, is used to estimate the parameters (σ_N , σ_S , *l*) (Kitanidis 145 and Shen, 1996).

- 146 The best linear unbiased estimator of β on the basis of Aitken (1935) is the 147 generalized-least-squares estimator, that is, the value of β that minimizes (*LAI* –
- 148 $X\beta$)^{*T*} $Q^{-1}(LAI X\beta)$. Thus,

149
$$\hat{\beta} = (X^T Q^{-1} X)^{-1} X^T Q^{-1} LAI$$
(4)

- 150
- 151 2.2. *Reduced major axis method*

To robustly assess the performance of the GR model, we compare the results from
GR and RMA models. We choose RMA method because it is regarded as the 'standard'
method for estimating LAI reference map in BigFoot project (Berterretche et al., 2005;
Cohen et al., 2003), which is a well known project linking in situ measurements, remote
sensing and models to validate MODIS products including LAI product. The form of
RMA is identical to a simple linear regression method:

158 $LAI = \beta_0 + \beta_1 X + \varepsilon \tag{5}$

159 Where X is DIV, NDVI, and RVI, respectively. ε is white noise residual. 160 RMA method is superior to traditional ordinary least squares regression when 161 both dependent (LAI in this study) and independent variables (DVI, NDVI, and RVI in 162 this study) are measured with errors (Cohen et al., 2003; Smith, 2009). The estimating of β_0 and β_1 is different with the traditional ordinary least square regression. The traditional 163 164 ordinary least square regression estimates the regression coefficients by minimizing the 165 sum of squares of the residuals, while RMA minimizes the areas of triangles formed by 166 the deviation of a point from the regression line in both horizontal and vertical directions (Smith, 2009). The equations for calculating β_0 and β_1 are $\beta_0 = \overline{LAI} - \frac{\sigma_Y}{\sigma_X} \overline{X}$ and $\beta_1 = \frac{\sigma_Y}{\sigma_X}$. 167

- 168
- 169 **3. Data**

170 3.1. Study Sites

171 Two cropland sites (AGRO and Plan-de-dieu sites) and two grassland sites 172 (Hulun Buir and Zhangbei sites) were used in this study. The AGRO site is from the 173 BigFoot project (http://www.fsl.orst.edu/larse/bigfoot/index.html), which is funded by 174 NASA'S Terrestrial Ecology Program (Morisette et al., 2006; Pisek and Chen, 2007). 175 Nine validation sites are in the BigFoot project with each of them covering a 5 km \times 5 km 176 extent (Morisette et al., 2006). The field LAI values in the AGRO site were measured by 177 the allometric destructive method. The Hulun Buir site is one of the validation sites for 178 the GLASS LAI product, which is a newly released LAI product generated by Beijing 179 Normal University, China (Liang et al., 2014). The coverage of the Hulun Buir site is 180 about 32 km × 28 km. The in situ LAI values in the Hulun Buir were measured by LAI-

181 2000. The Plan-de-dieu and Zhangbei sites are from the VALERI project

182 (http://w3.avignon.inra.fr/valeri/), which has served to provide high spatial resolution

183 maps of biophysical variables (e.g., LAI, fAPAR, fCover) to validate products derived

184 from satellite observations (e.g., VEGETATION, MERIS, POLDER, AVHRR, and

185 MODIS) (Baret et al., 2005). The VALERI project has 33 sites, each of them covering

around 3 km \times 3 km. The in situ LAI values in the VALERI project were measured by

187 LAI-2000 or hemispherical images.

188 The AGRO site is located in Bondville, Illinois, USA. The main crop types of the

189 AGRO site are corn and soybean (Pisek and Chen, 2007). The Plan-de-dieu site, with its

190 main crop being vineyards, is located at Cotes du Rhone Village, France (Rossello,

191 2007). The Hulun Buir and Zhangbei grassland sites are located in Inner Mongolia and

192 Hebei, China, respectively. The Landsat TM/ETM+ for AGRO and Hulun Buir sites were

193 employed in this study as high resolution remote sensing images, because they are

194 commonly used in up-scaling field measurements (Berterretche et al., 2005; Cohen et al.,

195 2003) and could be easily obtained. We chose SPOT-HRV for Plan-de-dieu and

196 Zhangbei sites because the Landsat TM/ETM+ corresponded to the date of in situ LAI in

these two sites has gaps and does not have good quality, while SPOT-HRV images have

198 been collected for many sites in VALERI project including Plan-de-dieu and Zhangbei

199 sites (Baret et al., 2005). The in situ LAI, TM/ETM+, and HRV data on the exact same

200 date were not available. Therefore the data on the closest dates were chosen. The detailed

201 information of the four sites is described in Table 1. The locations of the four study sites

and the corresponding distribution of the in situ LAI locations in each site are shown in

Figure 1.

Sites	UTM X Coord	UTM Y Coord	UTM Zone	Location	Vegetation types	Datasets used	Datasets when obtained	In situ LAI measurement method
AGRO	389764	4429295	16N	Illinois USA	Corn and Soybean	Field $7/24/2000$ Corn andLAI;SoybeanETM+; $7/15/2000$ Land2000cover		Allometric destructive means
Plan-de- dieu	655669	4895787	31N	Cotes du Rhone Village France	Vineyards	Field LAI; SPOT;	7/05-7/09/2004 6/29/2004	Hemispherical images
Hulun Buir	717675	5473425	50N	Inner Mongolia China	Grassland	Field LAI; TM; Land cover	6/26/2010 6/21/2010 2010	LAI-2000
Zhangbei	306354	4572278	50N	Hebei China	Grassland	Field LAI; SPOT;	8/08/-8/10/2002 8/23/2002	Hemispherical images



Figure 1. Study sites of the AGRO, Plan-de-dieu, Hulun Buir, and Zhangbei (the
background is the standard false color composited image, and the green points are the in
situ LAI locations).

210 *3.2. Data pre-processing*

- 211 Landsat TM/ETM+ data with 30 m spatial resolution used in this study were
- 212 downloaded from the USGS website (<u>http://glovis.usgs.gov/</u>). The TM/ETM+ data are
- 213 Level 1T data that have been systematically, radiometrically, and geometrically
- 214 corrected. A large proportion of images are contaminated due to the influence of aerosols,
- 215 clouds, and cloud shadows (Liang et al., 2001). The TM/ETM+ data were
- atmospherically corrected by the Landsat Ecosystem Disturbance Adaptive Processing
- 217 System (LEDAPS) (Masek et al., 2006). The two study areas, the AGRO and Hulun Buir

218	sites, were extracted using ENVI software (Figure 1). The SPORT-HRV data with a
219	spatial resolution of 20 m over the Plan-de-dieu and Zhangbei sites were obtained from
220	the VALERI project (see the link in 3.1). Though they were geometrically corrected, no
221	atmospheric corrections were applied to the images since no atmospheric data were
222	available (Rossello, 2007, 2008). Rossello (2007) stated that atmospheric effects were
223	assumed to be the same over the whole 3 km \times 3 km extent, since the SPOT images were
224	used to compute empirical relationships between reflectance and biophysical variables.
225	The biophysical variables in the VALERI project over most of the 33 sites were based on
226	SPOT-HRV top of atmosphere (TOA) reflectance (Baret et al., 2005). Following
227	previous studies, this study also used the SPOT-HRV TOA reflectance to obtain the LAI
228	values over the Plan-de-dieu and Zhangbei sites.
229	To evaluate the impacts of different vegetation indices on the GR and RMA
230	models, this study employed DVI, NDVI, and RVI. The forms of these vegetation indices
231	are: (Colombo et al., 2003; Huete et al., 2002).
232	$DVI = NIR - R \tag{6}$
233	NDVI = (NIR - R) / (NIR + R) ⁽⁷⁾
234	$RVI = NIR / R \tag{8}$
235	NIR is reflectance of near infrared band and R is reflectance of red band.
236	The scatter plots of DVI, NDVI, and RVI with the in situ LAI measurements at
237	the four study sites are shown in Figure 2. At the AGRO site, DVI, NDVI, and RVI of the
238	corn and soybean crop types have apparent boundaries. This study thus established the
239	GR and RMA models for these two crop types, respectively. The land cover data from
240	the BigFoot project was used to distinguish the corn and soybean over the AGRO site

(Table 1). As the Hulun Buir covered around 896 km², which may include other types of
vegetation (e.g., forest), the land cover data used in this study to mask the non-grassland
regions was provided by Tsinghua University (Table 1), China (Gong et al., 2013; Yu et
al., 2013).



245

Figure 2. The scatter plots of DVI, NDVI, and RVI with the in situ LAI at the AGRO,Plan-de-dieu, Hulun Buir, and Zhangbei sites.

247 Pla 248

The total in situ LAI measurements for the AGRO, Plan-de-dieu, Hulun Buir, and Zhangbei sites are 98, 26, 51, and 42, respectively. This study randomly selected around 65% of the LAI points to establish and specify the GR and RMA models. The 35% of the LAI points were used to validate the results. This was repeated another five times for the GR models, in order to cross validate the robustness of performance of the models.

- 234
- 255

257 **4. Results and Discussion**

258 4.1. Spatial covariance models

259 As stated in 2.1, the residuals for Equation (1) were assumed to be second-order 260 stationary with zero-mean, we calculated the experimental isotropic covariance of the 261 residuals using least square method (Li et al., 2013b). The experimental covariances were 262 modeled with exponential functions. The parameters of exponential functions were 263 obtained through RML method. Table 2 shows the parameters of exponential functions 264 for different VIs at four sites, respectively. The experimental and modeled covariances 265 are shown in Figure 3. The parameters of covariance function in the same site have very 266 similar values, which indicate similar spatial structure happens in the same site no matter 267 what the VI is. At different sites the parameters are quit different (Table 2), depending on 268 the locations of in situ LAI measurements and associations between LAI and VIs in that 269 site. In addition to nugget variance for DVI at AGRO (Corn) site, all of the nugget values 270 are larger than zero, which may be due to the heterogeneous of LAI of sub-samples 271 within each sample, since the in situ LAI value for each sample is calculated from sub-272 samples in that sample (Baret et al., 2005; BigFoot, 1999). For example, each in situ LAI 273 sample plot in Zhangbei site covers around 20 m x 20 m. In each sample plot, 12 sub-274 samples are used to calculate the corresponding LAI value for that sample plot (Baret et 275 al., 2005).

Table 2. Parameters of the covariance function

Site	VIs	σ_N	σ_{s}	l
	DVI	0.000	0.278	193.862
AGRO	NDVI	0.099	0.361	193.862
(Corn)	RVI	0.104	0.356	193.862

AGRO	DVI	0.069	0.184	142.228
(Soybean)	NDVI	0.067	0.184	142.228
	RVI	0.062	0.194	142.228
	DVI	0.003	0.010	1505.988
Plan-de-dieu	NDVI	0.003	0.011	1505.988
	RVI	0.003	0.011	1505.988
	DVI	0.053	0.212	2501.122
HulunBuir	NDVI	0.047	0.187	2501.122
	RVI	0.044	0.174	2501.122
	DVI	0.026	0.104	699.860
Zhangbei	NDVI	0.024	0.096	699.860
	RVI	0.022	0.088	699.860





281 Figure 3. The experimental and modeled covariance (blue circle is experimental 282 covariance, and red line is modeled covariance) 283

284 4.2. GR models for the four study sites

285 Table 3 shows the GR models for the AGRO, Plan-de-dieu, Hulun Buir, and 286 Zhangbei sites. The values in parentheses are standard deviations for slope and intercept. 287 The significance of slope and intercept are tested by Student's t test. Besides slopes for 288 NDVI and RVI in the AGRO (corn) sites, all slopes are significant at 1% level, indicating 289 the reliability of the models. The majority of intercepts are not significant at 1% level, 290 excepting the intercepts in Zhangbei site. The insignificance may be due to small 291 samples, such as the AGRO (corn) and Plan-de-dieu sites. The negative values of

intercept may be attributed to the uncertainty of retrieving DIV, NDVI, and RVI from
TM/ETM+ and HRV images, as there is no accurate atmosphere information for each
sites, thereby the band reflectance from these images has errors. In addition, the in situ
LAI values also have measurement errors. Therefore, the negative values of intercept are
shown when conducting statistical analysis.

297 The coefficient of determination (R^2) varies among different models in different sites. At the AGRO site, the R^2 value for corn ranges from 0.28 to 0.44, and for soybean 298 299 0.38 to 0.40. The R^2 value of DVI model is the highest for the AGRO site compared to the R² values for NDVI and RVI models. As with the AGRO site, the R² value of DVI 300 301 model in the Plan-de-dieu site is the highest. The R² value for the Hulun Buir and 302 Zhangbei grassland sites ranges from 0.53 to 0.61, 0.63 to 0.69, respectively. In contrast 303 to the cropland sites (i.e., the AGRO and Plan-de-dieu sites), the R² values of DVI models 304 over the two grassland sites are the lowest. Excepting for Zhangbei site, the R² values are 305 not high, which maybe because of the poor relationships between DVI, NDVI, and RVI 306 and original in situ LAI values (Figure 2). However, the GR models with DVI perform 307 best over the two cropland sites, while for the two grassland sites, the GR models with 308 DVI have the poorest performance.

309

 Table 3. GR models at the four study sites.

Site	VIs	R ²	Slope	Intercept
	DVI	0.44	14.62**	-2.29
AGRO			(4.02)	(1.81)
(Corn)	NDVI	0.28	23.56	-17.16
			(20.35)	(18.40)
	RVI	0.29	0.10	2.20
			(0.09)	(1.76)

AGRO	DVI	0.4	5.35**	-1.23*
(Soybean)			(1.09)	(0.56)
-	NDVI	0.4	8.55**	-6.23**
			(1.71)	(1.55)
-	RVI	0.38	0.05**	0.41
			(0.01)	(0.24)
	DVI	0.57	4.47**	-0.17
Plan-de-dieu			(1.01)	(0.14)
-	NDVI	0.53	2.53**	-0.16
			(0.61)	(0.14)
-	RVI	0.54	0.75**	-0.78*
			(0.18)	(0.29)
	DVI	0.53	15.46**	-1.25*
HulunBuir			(2.62)	(0.52)
-	NDVI	0.58	8.41**	-3.39**
			(1.28)	(0.79)
-	RVI	0.61	0.50**	-0.41
			(0.07)	(0.32)
	DVI	0.63	13.82**	-1.11**
Zhangbei			(2.13)	(0.34)
-	NDVI	0.65	4.84**	-1.11**
			(0.70)	(0.32)
-	RVI	0.69	0.66**	-0.75**
			(0.09)	(0.25)

310 * significant at 5% level, ** significant at 1% level.

311 *4.3.* Estimating and validating the reference LAI maps based on GR models

Figure 4 presents the reference LAI maps estimated by the GR models based on Table 3. The validation results are shown in Figure 5 and Table 4. Most of the R² values in Table 4 are nearly equal to the R² values in Table 3, which indicates that the GR models are robust. However, some GR models may not be robust (e.g., GR model with DVI for corn at the AGRO site). We discuss the problem in detail at the end of this

317	section. As mentioned in section 4.2, the low R^2 values for GR models at the AGRO,
318	Plan-de-dieu, and Hulun Buir sites may be due to the poor relationships of DVI, NDVI,
319	and RVI with in situ LAI observations. For example, there is one very low in situ LAI
320	observation at the AGRO (corn) and Plan-die-dieu sites, and one very high in situ LAI
321	observation at the Hulun Buir site. These abnormal in situ LAI observations may be
322	owing to measurement errors. Regardless, the R^2 values show the same pattern as that in
323	section 4.2. That is, in terms of R^2 values, the GR models with DVI have the best
324	performance over the two cropland sites, while the GR models with DVI at the two
325	grassland sites perform more poorly. The values of root mean square errors (RMSE)
326	indicate that all the sites have the same trend within same vegetation types, excepting for
327	the Plan-de-dieu site. The RMSE values are lowest for DVI at the AGRO site (0.88 for
328	corn and 0.59 for soybean). This implies that the standard deviation of the differences
329	between the estimated LAI based on DVI and the field LAI is lowest. However, at the
330	Hunlun Buir and Zhangbei sites, the RMSE values are highest for DVI (0.40 and 0.46,
331	respectively). In terms of bias, there are no clear common characteristics. For example,
332	the value of absolute bias for the AGRO (corn) site is lowest based on DVI, while for the
333	AGRO (soybean) site, the value of absolute bias is lowest based on RVI. In summary, the
334	GR models based on DVI have the best estimations for the two cropland sites, while for
335	the two grassland sites, the GR models based on DVI perform poorly.

Table 4. Statistics of estimated LAI of the GR and RMA models compared to the in situ LAI.

LAI.							
Site	VIs		\mathbf{R}^2	R	MSE	b	ias
Sile		GR	RMA	GR	RMA	GR	RMA
	DVI	0.23	0.23	0.88	0.89	0.05	0.10
AGRO	NDVI	0.18	0.18	0.94	1.10	-0.17	0.01

(Corn)	RVI	0.17	0.17	0.94	1.10	-0.16	0.01
	DVI	0.43	0.43	0.59	0.68	-0.15	-0.22
AGRO	NDVI	0.29	0.29	0.73	0.99	-0.22	-0.33
(Soybean)	RVI	0.38	0.38	0.60	0.68	-0.12	-0.16
	DVI	0.52	0.52	0.16	0.17	0.10	-0.12
Plan-de-dieu	NDVI	0.43	0.43	0.16	0.17	0.08	-0.10
	RVI	0.45	0.45	0.16	0.17	0.08	-0.10
	DVI	0.45	0.45	0.40	0.43	-0.11	-0.12
HulunBuir	NDVI	0.55	0.55	0.39	0.48	-0.14	-0.15
	RVI	0.56	0.56	0.38	0.43	-0.15	-0.16
Zhangbei	DVI	0.53	0.53	0.46	0.52	-0.02	0.02
	NDVI	0.67	0.67	0.38	0.42	-0.01	0.02
	RVI	0.63	0.63	0.43	0.50	0.05	0.10







(6)

LAI (m²/m²

(1)

GRM DVI

(4)



(5) Plan-de-dieu



Figure 4. Reference LAI maps estimated by the GR models at the AGRO, Plan-de-dieu,
Hulun Buir, and Zhangbei sites.





351 study used cross validation. Considering the intensive computation of the GR models that

352 involve spatial covariance modeling and geostatistical estimation, this study was repeated

353 five times by randomly selecting 65% of the LAI points for establishing the GR models,

- 354 with the remainder of the LAI points used for model validation. The mean RMSE values
- 355 (μ_{RMSE}) of the five repetitions were calculated following previous studies Lee et al.
- 356 (2008a, b). Figure 6 shows the results of cross validation. The blue bar is the μ_{RMSE} of the

357 five repetitions for each GR model, the black error bar is $\mu_{RMSE} \pm \sigma_{RMSE}$ (σ_{RMSE} is the 358 standard deviation) of the five repetitions for each GR model, and the brown square is the 359 RMSE value from Table 4. In comparison to the μ_{RMSE} in Figure 6, most of the RMSE 360 values in Table 4 are nearly within $[\mu_{RMSE} - \sigma_{RMSE}, \mu_{RMSE} + \sigma_{RMSE}]$, which indicates that 361 the GR models are robust. The RMSE value of the GR model for DVI at the AGRO 362 (corn) site slightly exceeds the upper limits of the error bar ($\mu_{RMSE} + \sigma_{RMSE}$), which 363 confirms that the GR model with DVI for corn at the AGRO site is not robust. This is 364 presumably due to the poor association of DVI and the in situ LAI values (Figure 2). The 365 RMSE values of the GR model for DVI and RVI at the Zhangbei site also exceed upper 366 limits of the error bar, which may be due to the limited repetitions. More repetitions are 367 needed for robust validation.



368

Figure 6. Cross validation for the GR models

370 4.4. Comparing the results of GR and RMA models

371	For robust assessment of the performance of the GR models, the results from the
372	GR and RMA models were compared. Based on equation (5), the high resolution
373	reference LAI maps estimated by the RMA model are depicted in Figure 7. The
374	validation results are displayed in Figure 8 and Table 4. In terms of R^2 , the GR models
375	have identical values with the RMA models at the four study sites. The RMSE values for
376	the GR models are lower than the RMA models for all of the sites, which may due to the
377	consideration of spatial correlations of regression residuals. The GR models have lower
378	biases than the RMA models, excluding the GR models with NDVI and RVI at the
379	AGRO (corn) site. In summation, the GR models improve the accuracy of reference LAI
380	maps compared to the RMA models.
381	In addition, the GR and RMA models had consistent performance at cropland and
382	grassland sites. Both GR and RMA models have the best estimating ability based on DVI
383	at the cropland sites (AGRO and Plan-de-dieu sites), while the GR and RMA models
384	perform poorly based on DVI at the grassland sites (Hulun Buir and Zhangbei sites).
385	



Figure 7. Reference LAI maps estimated by the RMA models at the AGRO, Plan-de-dieu, Hulun Buir, and Zhangbei sites.





394 Zhangbei
395 Figure 8. Validation results of the RMA models at the AGRO, Plan-de-dieu, Hulun Buir,
396 and Zhangbei sites.

398 5. Conclusions

399 Spatial scale issue commonly exits in remote sensing studies. Van der Meer et al. 400 (2001) explored spatial scale effects on vegetation indices estimation through calculating 401 vegetation indices, including NDVI, perpendicular vegetation index, weighted difference 402 vegetation index, etc., from the Medium Resolution Imaging Spectrometer (MERIS) at 403 the spatial resolutions ranging from 6 to 300 m. The proposed way to validate coarse 404 resolution remote sensing products is using fine reference maps derived from up-scaling 405 in situ measurements. This study up-scaled the field LAI measurements to high resolution 406 LAI reference map through linking the in situ LAI measurements and Landsat TM/ETM+ 407 and SPOT-HRV data using the geostatistical regression method. To analyze the 408 discrepancy of employing different vegetation indices on estimating LAI reference maps, 409 this study established the GR models for DVI, NDVI and RVI. To further assess the 410 performance of the GR model, this study compared the results from GR and RMA 411 models. The results show that the performances of GR models over the cropland and 412 grassland sites are different. The GR models based on DVI provide the best estimation at 413 the cropland sites (AGRO and Plan-de-dieu sites), while the GR models perform poorly 414 based on DVI at the grassland sites (Hulun Buir and Zhangbei sites). By considering the

spatial/temporal correlations of in situ LAI observations and high resolution DVI, NDVI,
and RVI data, this study reveals that the performance of the GR models is better than the
RMA models in terms of RMSE and bias.

418 In summary, the GR method inherits the merits from both traditional geostatistical 419 methods and regression methods. Compared to regression methods (e.g., RMA), the GR 420 method is improved in accounting for the spatial/temporal correlation of residuals from 421 the regressions of LAI observations and high resolution remote sensing data (e.g., DVI, 422 NDVI and RVI data in this study). In contrast to traditional geostatistcal methods (e.g., 423 Kriging), the GR method attempts to provide better estimating of unknown points by 424 exploring the association between high resolution remote sensing data and field 425 observations. Our study confirmed the performance of the GR models is better than the 426 RMA models in terms of RMSE and bias, which indicates the potential of GR method to 427 up-scale other in situ biophysical and geophysical measurements (e.g., fAPAR and soil 428 moisture) to high resolution reference data to validate other coarse resolution products.

429

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